

**Data**  
**Scientific Method**  
 1. Observation \* units (metrics)  
 2. Define the Problem \* measuring  
 3. Test/Experiment \* sig. figs.  
 4. Hypothesis \* Data  
 5. Collect Data/Manipulate Manipulation  
 6. Conclusion

**Accuracy vs. Precision**  
 Accuracy – closeness of results to a standard  
 Precision – closeness of results to each other  
 \*use same piece of equipment to collect data\*

**Qualitative vs. Quantitative**  
 Qualitative – more on precision than accuracy  
 Quantitative – numbers count and are important

**Sig. Figs.**  
 Addition and Subtraction:  
 \*least # places after decimal  
 Multiplication:  
 \*places after decimal count as sig. figs.  
 2.5 cm = 1 in

**Vectors**  
 Vectors (velocity) – has BOTH *magnitude* and *direction*  
 Scalars (speed) – has *magnitude* ONLY  
 \*time, mass, volume

**Metric System Abbr.**  
 Mm - km - hm - dkm - m  
 dm - cm - mm - Mm(E-6) - nm(E-9)

**Multi-Component Vectors**  
 1. 18m due S  
 2. 22m, 47deg. S of W  
 3. 10 m, 78deg. N of W  
 4. 30 m due E

\*(W&E) Sum of the  
 $V_x = (0) + (-22 \cos 47) + (-10 \cos 78) + (30) = 12.9m$

\*(N&S) Sum of the  
 $V_y = (-18) + (-22 \sin 47) + (10 \sin 78) + (0) = -24.3m$

\*Resultant  $v =$   
 $((12.9)^2 + (24.3)^2)^{1/2} = 27.5m$   
 $\theta = \tan^{-1}(24.3/12.9) = 62.0deg$   
 $R = 28m, 62deg S of E$

**Kinematics**  
**Displacement**  
 If + it's AWAY  
 If - it's TOWARD

**Velocity (m/s)**  
 Use ONLY when *SPEED is CONSTANT*  
 1. does not include acceleration  
 2. does not include starting and stopping in the same place

**Acceleration (m/s/s)**  
 \*speeding up or slowing down  
 $a = \frac{v}{t}$

**Kinematic Formulas**  
**X Direction** **Y Direction**  
 $v = v_0 + at$   $-gt$   
 $\chi = \chi_0 + v_0 t + \frac{1}{2} at^2$   $-\frac{1}{2} gt^2$   
 $\chi = \chi_0 + \frac{1}{2} (v_0 + v) t$   
 $v^2 = v_0^2 + 2a(\chi - \chi_0)$   $-2g(\chi - \chi_0)$

Change  $\chi$  (o) to Y(o)

**Projectile Motion**  
**Half**  
 \* Y determines time in air  
 \*complement angles of 45deg have same range  
 $\chi = v \chi t$   $Y = \frac{1}{2} gt^2$   
 $T = \frac{\chi}{V \chi}$

**Full**  
 \* 45deg has max. range  
 Steps:  
 1.  $v_x \cos \theta_0 / v_0 \sin \theta_0$   
 2. Find the TIME (check Y)  
 3. Find the height / range  
 $\chi = v \chi t$   $t = \frac{Y}{\frac{1}{2} g}$   
 $(V_x = v_0 \cos \theta_0)$   $(V_y = v_0 \sin \theta_0)$   
 $y_{max} = \frac{v_0^2 \sin^2 \theta_0}{2g}$

**Force (N)**  
 - Causes a change in motion (causes acceleration)  
 - Is a VECTOR quantity  
**Equilibrium** – no acceleration, forces cancel, "at rest"

**Newton's Laws of Motion**  
 1. An object at rest will remain at rest until acted upon by an outside force  
**INERTIA** – directly related to mass

2. Acceleration is *directly* related to Force  
*indirectly* related to mass  
 $F = ma$  (1 kg m / s<sup>2</sup> = 1 Newton)

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3. Action = equal and opposite reaction  
 -can't have only one force  
 $F_a, b = -F_b, a$

**Normal Force**  
 - able to change until breaking point of whatever it's holding  
 - acts perpendicularly to "holding" object  
 - comes from ground (except water)

**Newtons**  
 $1 N = 0.225 lbs.$  Mass is constant  
 $F = ma$  -----  $F_w = mg$   $N \rightarrow kg$  (/ 9.8)  
 $kg \rightarrow N$  (x 9.8)

**Friction (Ff)**  
 1. two or more things must be touching  
 2. energy is transferred (heat, sound, etc)  
 3. texture matters... NOT SURFACE AREA  
 $\mu =$  coefficient of friction (Ratio of parallel force to perp. Force)  
 $\mu = \frac{F_f}{F_N}$  (3 decimal places)  
 $F_f = \mu mg$   $F_f = F_w$  (on flat surface)  
 $\mu = \tan \theta$  (when  $v$  is constant)  
**Pressure:**  $P = \text{Force/area}$

4. opposes motion which causes deceleration

5. **static** – "starting Ff" not moving (rolling)  
 greater force than kinetic  
**kinetic** – moving (rolling, sliding, fluid)

**Equilibrium**  
 Translational: the sum of forces equal zero  
 Rotational: the sum of torques equals zero  
 Complete: must have BOTH

**Center of Gravity**: center of distribution of mass

**Torque**  
 Force with leverage causes rotation  
 Leverage: distance from fulcrum to force  
 \*Directly related to torque  
 $\tau = F$  (perp.)  $l$

**Circular Motion**  
 Moving at a constant speed while accelerating  
 $A = v \rightarrow$  speed: constant  
 dxn: constantly changing

**Centripetal Acceleration**  
 Inward seeking  $a_c = \frac{v^2}{r}$

**Centripetal Force**  
 Causes centripetal acceleration  
 $F_c = m a_c$  ( $F = m a$ )  
 $F_c = \frac{m v^2}{r}$  (N)

You MUST have cent. F to keep something moving in a circle

Centrifugal: body's interpretation of cent. F  
 DOES NOT EXIST  $\rightarrow$  feels inertia

Rotation: spinning on axis within object  
 Revolution: spinning on axis outside of object

**Linear / Angular**  
**Linear**: speed = distance / time  $\rightarrow$  radius matters  
 57.3deg = 1 RADIAN  
 1 rotation =  $2\pi$  Radians = 360 degrees

**Angular**: speed = # rotations or revolutions / time  
 $\rightarrow$  radius does NOT matter  
 \* by doubling the angular speed you double the # of rotations

Linear	Angular
$\chi$ (m)	$\chi = r\theta$ $\theta$ (RAD)
$v$ (m/s)	$v = r\omega$ $\omega$ (RAD / s)
$a$ (m/s/s)	$a = r\alpha$ $\alpha$ (RAD / s / s)
$F$ (N)	$Ft = \tau$ $\tau$ (Nm)
Mass (m)	$I$ (mr)
$F = ma$	$\tau = I\alpha$
For linear	$\omega = \omega_0 + \alpha t$
See other corner	$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$
	$\omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0)$

**Rotational Inertia**  
 Resistance to begin or stop rotation

- Depends on amount of mass AND where it is placed

**Solid Sphere**  $\rightarrow 2/5 mr^2$  **Solid Disk**  $\rightarrow 1/2 mr^2$   
**Hollow Sphere**  $\rightarrow 2/3 mr^2$  **Hollow Disk**  $\rightarrow 1 mr^2$

- Velocity is indirectly related to Inertia
- Shape of object spinning makes the difference while spinning

3 Forces acting upon an object in circular motion

- Centripetal Acceleration ( $A_c$ )
- Angular Acceleration ( $\alpha$ )
- Linear Acceleration ( $a$ )

**Conservation Laws**  
**Momentum (N s)**  
 Moving inertia (Newton's 2<sup>nd</sup> law)  
*Momentum IS inertia...Inertia is NOT momentum*  
 Momentum is DIRECTLY related to mass and speed  
 $p = mv$  (N s)

- causes body to want to fly off tangent

**Impulse**  
 A change in momentum (how you feel p change)  
 Force:  $F = ma \rightarrow F = m \frac{\Delta v}{\Delta t}$

Time: \* hidden variable\*  
 $F \Delta t = m \Delta v = \Delta p$

**Conservation of Momentum**  
 In the absence of an external force, the total momentum of a system is constant  
 $m_1 v_1 + m_2 v_2 = m_1 v_1 + m_2 v_2$

**Work (J)**  
 \* Need to apply force  $W = Fd$   
 \* implies motion

**Power ( watt - w )**  
 $P = \frac{W}{t} = \frac{Fd}{t} = \frac{F \cdot v}{t} = F \cdot \frac{v}{t} = F \cdot a$   
 $\frac{J}{s} = \frac{1 w}{s} = \frac{N m}{s} = \frac{1 kg \cdot m^2}{s^2}$   
 1 horse power = 746 w

**Energy**  
 Ability to do work  
**Mechanical**: energy of motion or position  
**Kinetic (K)**: motion  
 $K = \frac{1}{2} m v^2$  (J)  
**Potential (U)**: position  
 $U = mgh$  (J) ( $W = Fd$ )  
 When not given distance... (or force)  
 $W = \frac{1}{2} m v^2 - \frac{1}{2} m v_0^2$  ( $W = \Delta K$ )  
 (K final) – (K initial)

**Conservation of Energy**  
 Energy change from one to the other w/o any net loss  
 $U_{top} = K_{bot}$  ( $mgh = 1/2 mv^2$ )

**Wave Motion**  
**Simple Harmonic Motion**  
 A repeating motion in which the acceleration is directly related to the displacement (distance away from the equilibrium) and always directed towards equilibrium.

$T = 2\pi \sqrt{\frac{m}{k}}$   $f = 1/T$

**Cosine Curves**  
 $Y = A \cos B(x - C) + D$   
 A = amplitude (0): how much energy it has  
 CosB = period (2  $\pi$  /  $T$ ): time, 1 oscillation  
 C = horz. Shift: human error  
 D = vert. Shift: distance, to x-axis

**Waves**  
 \* Graphed SHM, transfer of energy  
**Vibration**: WORK to get energy  
**Propagates**: what energy moves through  
**Mechanical (light)**: Needs a medium  
**Electromagnetic (sound)**: does NOT need a medium  
 More dense – better less dense – better

**Mechanical Waves**  
**Transverse**: medium vibrates perp. to energy  
 Most common ex. Guitar string, slinky  
**Longitudinal**: medium vibrates para. to energy  
 Has compressions ex: sound  
 Surface: both para. and perp. to energy  
 "physics bob" ex: earthquakes, waves

**Principle of Superposition**  
 Constructive Interference: added  
 Destructive: subtracting (adding negatives)  
 $V = \frac{\lambda}{T}$   $V = \lambda f$

**Standing Wave**  
 A continuous wave train of equal amplitude (RAD), wavelength (m), and frequ. (Hz) / (sec) in the same medium creating nodes and antinodes.  
**Boundary**: change in medium  
 (part of energy gets reflected, part gets absorbed)  
**rigidity**: how much energy gets ABSORBED  
 close rigidity  $\rightarrow$  more absorbed  
 different rigidity  $\rightarrow$  more reflected

**Interference in Diffraction**  
 Crest + crest = antinode Crest + troph = node

**Sound**  
 A range of longitudinal wave frequ. to which the human ear is sensitive  
 Infra sonic sonic spectrum ultra sonic  
 (below 20 Hz.) (20 Hz – 20,000 Hz) (20,000 Hz +)

- production**: needs vibration
- transition**: needs a medium  $\rightarrow$  air
- reception**: must be heard  
 $V_{sound} = 340 m/s$   
 $V_{sound} = 331 + .6(Temp.)$

**Intensity**: measurable  
 How loud a sound is \* the time of flow of energy per unit area  
 $I = \frac{Pow.}{Amp} (P = \frac{W}{t})$   
 Intensity is DIRECTLY related to amplitude  
 Damping: further you get from the center  $\rightarrow$  quieter it will be  
**Inverse Square Law**:  $I_1 r_1^2 = I_2 r_2^2$

**Volume (B)**: subjective (decibels)  
 Relative Intensity Level  $\rightarrow$  loudness level

Volume is DIRECTLY related to Intensity  
 Volume is DIRECTLY related to Frequency  
 $f_{standard} = 1,000 Hz.$

Intensity Range  
 Threshold of hearing ( $I_0$ ) =  $1 \times 10^{-12} w / m^2$   
 Threshold of sound =  $1 w / m^2$   
 $\beta = 10 \log \left( \frac{I}{I_0} \right)$   
 $1 \times 10^{-12} w / m^2$   
 "How many powers of 10 are in that number?"  
 Decibel =  $\frac{w}{m^2}$

**Pitch and Tone**  
 $I \rightarrow$  volume  $f \rightarrow$  pitch  
**Notes and tones**: pitch with recognizable frequencies  
**Laws of Pitch**:  
 1.  $f$  is INDIRECTLY related to length  
 2.  $f$  is DIRECTLY related to tension (Ft)  
 3.  $f$  is INDIRECTLY related to diameter (d)  
 4.  $f$  is INDIRECTLY related to density (D)

**Beats**: the resultant interference pattern of 2 notes close in frequency but not exact  
 Create nodes (sharps and flats)  
**Doppler Effect**: the apparent change in frequency of a sound due to the relative motion of either the observer or the source of the

**Resonate**: when you cause something to vibrate at its natural frequency  
**Music**  $\rightarrow$  repeating wave pattern  
**Noise**  $\rightarrow$  not repeating wave pattern  
**Consonance**  $\rightarrow$  sounds GOOD  
**Dissonance**  $\rightarrow$  sounds BAD

Decibel:  

I	B
$1 \times 10^{-12}$	0 db
$1 \times 10^{-11}$	10 db
$1 \times 10^{-10}$	20 db
---	---
$1 \times 10^{-2}$	100 db
$1 \times 10^{-1}$	110 db
1	120 db

**Natural Frequencies**  $f = 1/70 / Hz$   
 Brass/String

n	name	symm	wavl ( $\lambda$ )	l	f
f	fund.	1 <sup>st</sup> har.	2l	1/4 $\lambda$	v/4l
f2	1 <sup>st</sup> ov.	2 <sup>nd</sup> har.	l	$\lambda$	v/l
f3	2 <sup>nd</sup> ov.	3 <sup>rd</sup> har.	2/3l	3/2 $\lambda$	3v/2l
f4	3 <sup>rd</sup> ov.	4 <sup>th</sup> har.	1/2l	2 $\lambda$	2v/l

$f_n = \frac{v}{\lambda_n}$   $h_n = \frac{2l}{\lambda_n}$   $f_n = N v_f$

Woodwind

n	name	symm	wavl ( $\lambda$ )	l	f
f	fund.	1 <sup>st</sup> har.	4l	1/4 $\lambda$	v/4l
f2	---	---	---	---	---
f3	1 <sup>st</sup> ov.	2 <sup>nd</sup> har.	4/3l	3/4 $\lambda$	3v/4l
f4	---	---	---	---	---
f5	2 <sup>nd</sup> ov.	3 <sup>rd</sup> har.	4/5l	5/4 $\lambda$	5v/4l

$f_n = \frac{v}{\lambda_n}$   $h_n = \frac{4l}{\lambda_n}$

**Instruments**  
**String**  
 Produced by: plucking string, bowing  
 Change pitch: length, diameter, tension, density

**Brass**  
 Produced by: buzzing mouth piece  
 Change pitch: length of pipe (valves), buzzing

**Woodwind**  
 Produced by: reed vibrating  
 Change pitch: pads, holes  
 Edge tones: narrow streams of air split by edge  
**Helmholtz Resonance**: edge tone with bottle (open hole)

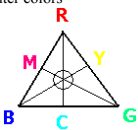
**Light**  
**Particle** **Wave**  
 + Newton said so + Thomas Young – 2 slit ex  
 + Beams / Waves + reflection, refraction,  
 + travel in straight lines + diffraction, interference  
 + Hertz – light is energy  
 + Einstein – wave particle duality  
**Polarized Light**: Light oriented to one plane (calc.)  
**Liquid Filter Display**: lets only one degree of light in  
**Visible Spectrum**:  
 Radio \* Micro \* Infrared \* Ultraviolet \* Xrays \* Gamma  
 Big wavelength  $\rightarrow$  Small wavelength  
 Red Orange Yellow Green Blue Indigo Violet  
 Transparent: see through it and light passes  
 (Windows, glass)  
 Translucent: can NOT see through it, light passes  
 (frosted glass)  
 Opaque: can NOT see through it, NO light passes  
 Source: makes and emits light  
 Luminous: sun  
 Luminate: moon  
 Light Year: takes 8.3 min. to get light from sun  
 Dispersion: breaking up light into colors (prism)

**Colors**  
 Cones in eye pick up 3 primary colors of light  
**Additive**

Primary	Secondary
BLUE	YELLOW
RED	CYAN
GREEN	MAGENTA

\* More than one light source

\* Brighter colors



Subtractive

Primary  
YELLOW  
CYAN  
MAGENTA

Secondary  
BLUE  
RED  
GREEN

\* only one light source  
\* darker colors

**Shades of Colors**

Hue: proportion of color  
Saturation: amount of white mixed with color  
Brightness: amount of black mixed with color

**Reflection**

Smooth:  $\theta_i = \theta_r$   
Diffuse: "scatters light" obeys laws still

**Refraction**

Index of Refraction  $n = 3 \times 10^8 \frac{v}{c}$

(speed in whatever medium)

Air: 1.00 Water: 1.33 Glass: 1.52

**Snell's Law**

\* n is INDIRECTLY related to  $\theta$   
\* n is INDIRECTLY related to speed  
\* v is DIRECTLY related to  $\theta$   
 $n_1 \sin \theta_1 = n_2 \sin \theta_2$

**Lasers**

Critical angle ( $\theta_c$ ): the  $\theta_i$  that produces the angle that is larger than  $\theta_c$ .

Total Internal Reflection: no refraction

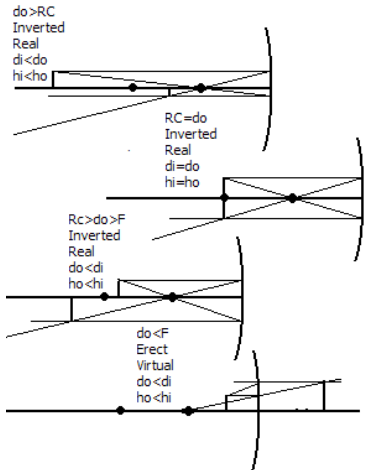
**Optics**

Reflection: mirrors  
Refraction: lenses

**Mirrors**

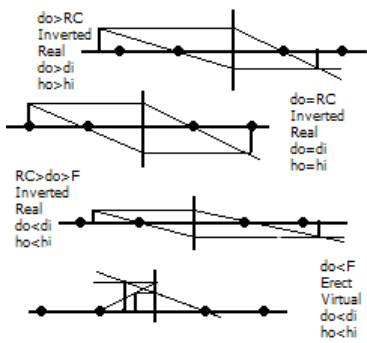
Concave: converging and upside down after foc. pt  
Convex: diverging, upright and smaller  
Magnification:  $M = \frac{hi}{ho} = \frac{di}{do} = \frac{f}{do-f}$

$hi = \frac{ho di}{do}$   $f = \frac{do di}{do + di}$   $do = \frac{di f}{di - f}$   $di = \frac{do f}{do - f}$



**Lenses**

Concave: corrects nearsightedness diverging  
Convex: corrects farsightedness converging



If you have this	Do this	To get this
N	$\times .225$	lb.
lb.	$\div .225$	N
N	$\div 9.8$	Kg
Kg	$\times 9.8$	N

lb.	$\times .454$	Kg
Kg	$\div .454$	lb.

3.  $x_i = 0$   
 $x = 12$   
 $x_f = 15$   
 $v = 0$   
 $a = -$   
 $a = -6.73$   
 $F_u = 66 - (9.8)$   
 $\mu = ?$

$x^2 = v_i^2 + 2a(x - x_i)$   
 $0 = 0 + 2a(12 - 0)$   
 $0 = 24a$   
 $a = -6.73$

$F_f = ma = (6.73)(9.375) = 63.09$

$\mu = \frac{F_f}{F_u} = \frac{63.09}{66} = .95596$

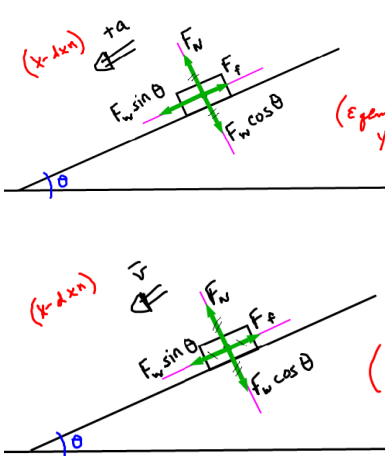
$\mu = 0.956$

3.  $\sum F_y = \sum F_x$   
 $(7.2 + 28.3) = (2.5 + 47.5)$   
 $45.5 = 50.0$   
 $\therefore F_{up} = 455 N$

$\sum \tau_c = \sum \tau_{cc}$   
 $(35)(.5) + (47.5)(1.5) = (28.3)(3) + (45.5)(2)$   
 $1.468 = 1$

$F_{ur} = 455 N, 1.4 m \text{ from left end}$

**Incline Graphs**

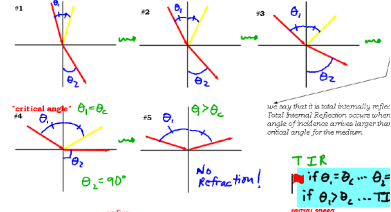


[EX] How much momentum does a 6.0 kg object have if it is moving at 3.0 m/s? What force would it take to bring it to rest in 2.0 seconds?

$p = mv = (6)(3) = 18$   
 $p = 18 N \cdot s$

$F = \frac{\Delta p}{\Delta t} = \frac{-18}{2} = -9$   
 $F = 9.0 N \text{ opposite dir.}$

**Total Internal Reflection**



[EX] An 18 cm flywheel slows from 8.0 rev/sec to 3.0 rev/sec over a 3.5 second time interval. Find its angular deceleration & its angular & linear displacements.

$\omega = 8 \text{ rev/sec} = 50.26 \text{ rad/s}$   
 $\omega = 3 \text{ rev/sec} = 18.85 \text{ rad/s}$   
 $t = 3.5 \text{ sec}$   
 $\alpha = -9.0 \text{ rad/s}^2$

$\theta = \omega_i t + \frac{1}{2} \alpha t^2$   
 $\theta = (50.26)(3.5) + \frac{1}{2}(-9.0)(3.5)^2$   
 $\theta = 120 \text{ rad}$

$s = r\theta = (0.18)(120) = 21.6 \text{ m}$

[EX] Buddy rides his bike off the top of a 24.5 m high building going 6.25 m/s. What will his range be?

$x = v_x t$   
 $x = (6.25)(2.324) = 14.0 m$

[EX] A football is kicked at 18 m/s, 42° above the horizontal ground. Find both its maximum height and range?

$x = v_x t$   
 $x = (15.4)(2.4) = 37.0 m$

3.  $K = 22$   
 $v_i = 8.96 \text{ m/s}$   
 $v_f = 6.0 \text{ m/s}$   
 $m = 6.122 \text{ kg}$   
 $F_f = ? N$   
 $a = -$   
 $x = 0$   
 $x_f = ? m$   
 $t = ? \text{ sec}$

$F_f = \mu F_n = (.22)(60) = 13.2$   
 $F_f = 13.2 N$

$a = \frac{F_f}{m} = \frac{13.2}{6.122} = 2.156$

$x = v_i t + \frac{1}{2} a t^2$   
 $0 = (8.96)t + \frac{1}{2}(-2.156)t^2$   
 $t = 9.16 \text{ sec}$

3.  $\sum F_y = \sum F_x$   
 $(55 \sin 35) + (45 \sin 75) = 65 + 35$   
 $75.013 = 100$   
 $\therefore F \text{ is up } \& \text{ is } 25 N$

$\sum \tau_c = \sum \tau_{cc}$   
 $(65)(1.5) + (35)(5) = (95 \sin 75)(4) + (25)(2)$   
 $3.945 = 1$

$F = 2.5 N, \text{ up}, 3.9 m \text{ from left end}$

5. (open)  
 $f_1 = \frac{v}{2l} = \frac{(17)(344)}{(2)(.86)} = 200$   
 $v = 344 \text{ m/s}$   
 $f_1 = ? \text{ Hz}$   
 $f_1 = 200 \text{ Hz}$

(closed)  
 $f_1 = \frac{v}{4l} = \frac{(17)(344)}{(4)(.86)} = 100$   
 $f_1 = 100 \text{ Hz}$